

Sprint 7 Planning

20181123 : Sprint 7 Planning Meeting Minutes

Attendees: Nicolas Gonzalez, Emmanuel Perez

Start time: 3:30 pm

End time: 4:00 pm

After discussion, the velocity of the team were estimated to be 12.

The product owner chose the following user stories to be done during the next sprint. They are ordered based on their priority.

- User Story <Users should have a realistic environment to drive the car on>
 **SPRS-13** - Users should have a realistic environment to drive the car on DONE
- User Story <User should be able to send API calls to reverse the car>
 **SPRS-22** - User should be able to send API calls to reverse the car DONE
- User Story <User should be able to reset the platform to restart the pawn to its default position>
 **SPRS-23** - User should be able to reset the platform to restart the pawn to its default position DONE
- User Story <User should be able to control the python client using a Controller to control the car and game hud>
 **SPRS-24** - User should be able to control the python client using a Controller to control the car and game hud DONE
- User Story <User should be able to send API calls to toggle on and off the front cameras>
 **SPRS-25** - User should be able to send API calls to toggle on and off the front cameras DONE
- User Story <User should be able to see the frame rate of the simulation in the hud, to monitor its performance>
 **SPRS-26** - User should be able to see the frame rate of the simulation in the hud, to monitor its performance DONE

The team members indicated their willingness to work on the following user stories.

- Nicolas Gonzalez
 - User Story <Users should have a realistic environment to drive the car on>
 **SPRS-13** - Users should have a realistic environment to drive the car on DONE
 - User Story <User should be able to reset the platform to restart the pawn to its default position>
 **SPRS-23** - User should be able to reset the platform to restart the pawn to its default position DONE
 - User Story <User should be able to control the python client using a Controller to control the car and game hud>
 **SPRS-24** - User should be able to control the python client using a Controller to control the car and game hud DONE
 - User Story <User should be able to see the frame rate of the simulation in the hud, to monitor its performance>
 **SPRS-26** - User should be able to see the frame rate of the simulation in the hud, to monitor its performance DONE
- Emmanuel Perez
 - User Story <User should be able to send API calls to reverse the car>
 **SPRS-22** - User should be able to send API calls to reverse the car DONE
 - User Story <User should be able to send API calls to toggle on and off the front cameras>
 **SPRS-25** - User should be able to send API calls to toggle on and off the front cameras DONE